# (1) OLBUS OF THEM ANDERSON

Aim: To study the given Microprocessor Trainer Kit and to familiarize with the various Hardware and Software specifications

# **Hardware specifications:**

(1) FREQUENCY: CPU gets Clock signal from Clock generator 8284 which uses a quartz Crystal of frequency,  $14.318$  MHz. Processor Clock frequency =  $(Crystal frequency)/3 = Crystal$  $14.318/3 = 4.77 \text{ MHz}$ . PCLK signal frequency of VXT Bus connector =  $(4.77 \text{ MHz})/2 =$ 2.385 MHz.

# (2) MEMORY:

# $(a)$  EPROM:

16 KB Intel 2764 (8 KB Chip)  $-2$  Nos.

Memory Map: F0000 H to F3FFF H (Total 16KB)

(b) SRAM (Static RAM):

6264 (8 KB Chip) - 2 Nos.

Memory Map: 00000 H to 03FFF H (Total 16KB) User area of RAM - 01000 H to 03FFF H



 $4000H = 16K$  and so on.  $400H = 1K$ ;  $800H = 2K$ ;  $1000H = 4K$ ;  $2000H = 8K$ ;

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Important Commands and description:

# - is the Command Prompt

<cr> - Carriage Return (Enter Key)

1) Assemble Command: - will generate op-code from the mnemonic entered #A  $\leq$ cr>

After entering the 'A' command, the Kit displays: 'Line Assembler' Then it asks the starting address. Here enter the starting address. It can be any number in the range 1000 to 3FFF (i.e., user area of RAM)

2) Unassemble (Disassemble) Command: - will generate mnemonic from the op-code

#U <cr>

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After entering the 'U' command, the Kit displays: 'Disassembler' Then it asks the starting address. Here enter the starting address. It can be any number in the range 1000 to 3FFF (ie, user area of RAM)

3) Substitute memory Command: (to modify or view memory content - byte or word)

#SB <addr> <cr> ; view or modify byte

#SW <addr> <cr> : view or modify word

The address (addr) can be entered in either 'Segment; Offset' form or only 'Offset form'.

Use Enter Key for incrementing memory address

Use - (minus) Key for decrementing memory address

Dot (.) command can be used for terminating a Command and to return to the Command Prompt.

4) Register view /modify Command:- to view/modify register contents  $HR \leq$ cr>

**Initial values of Register Contents:**  $AX = 0000H$ :  $BX = 0000H$ :  $CX = 0000H$ :  $DX = 0000H$ 

 $SP = 0800H$ :  $BP = 0000H$ :  $SI = 0000H$ :  $DI = 0000H$ 

 $CS = 0000H$ :  $DS = 0000H$ ;  $SS = 0000H$ ;  $ES = 0000H$ 

 $IP = 1000H$ ;  $FL = 0000H$ ;

- 5) Trace Command (Single step Execution): This helps the user to execute programs in steps (i.e., Single step mode)
- That is, executing Instruction by Instruction. This is helpful in debugging the programs.  $\#TR \leq addr > \leq cr$

Procedure:

- i) Enter the Trace command as above.
- ii) Now the first instruction is executed and the registers are automatically updated.
- iii) The next instruction to be executed and the memory locations are displayed.
- iv) To view the register contents after execution of each instruction. Press the dot (.) key for command termination and to return control to the monitor program. Here type the # R command to view the Register contents, or #SB or #SW command to view the memory contents. Again Press the dot key for command termination and to return control to the monitor program. To continue single step execution, from where it has stopped, enter the Command '#TR' alone, without any argument.

6) Normal Execution Command: - GO command

GO command is used to RUN a program. This command transfers control of the CPU from the Monitor program to User Program.

Syntax:  $GO$  <start addr> <cr>

#### Procedure:

- i) Type GO command and the address from where execution should start.
- ii) Now the control is transferred to the User program at the entered address location and the display shows 'Executing ...', since the Last Instruction used in the program is HLT. Or, equivalently a JMP instruction can be used instead of HLT, which will put the execution in an infinite Loop. For example: HERE: JMP HERE
- iii)To Exit from execution and to return control to the monitor program, press RES (Reset key) or INT (Interrupt key). But in this case the contents of registers will be cleared and hence cannot be observed.

'Dot' command will not work for terminating the execution, in this situation.

Notel: RES Key can also be used for breaking an infinite loop execution. INT key can also be used for Single Step execution

Note2: In the Keyboard, in the case of Keys having two characters written on a Key (for example the #Key), the upper Character is obtained by depressing the Shift Key first, then releasing the finger and then depressing the Character Key. Simultaneous depressing of the Shift Key and the Character Key will not work.

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7) Execution with Break Point: - (ie, GO command with break point)

Syntax: GB <start addr> <end addr> <cr>

When the execution reaches the end address, execution automatically stops and the control is returned to the Command Prompt. Now the register contents can be observed using #R command or the memory contents by the #SB or #SW commands. This command is useful in observing register contents as they are not cleared since we are not using the RES or INT keys for terminating execution in this case.

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Aim: To add two 16-bit unsigned integer numbers stored in memory locations and to store the 16-bit sum into memory locations.

#### Algorithm:

Assumption: It is assumed that the numbers to be added are stored in consecutive memory locations. Step 1: Start.

Step 2: Initialise a register to hold carry, to zero. Step 3: Bring the first number from memory into another register

Step 4: Add the second number from memory to the contents of the above register.

Step 5: If a carry is not generated, go to Step 7.

Step 6: Increment the Carry holding register.

Step 7: Store the result of addition into the next consecutive memory location.

Step 8: Store the contents of the Carry holding register into the next memory location.

Step 9: Stop

Assembly language Program:



Sample Input:



Note 1: Forward JMP and Forward CALL instructions: In this case the 'Target Address'. JMP and CALL instructions are not known before hand until we reach the Target address low To resolve such problem, use the 'Self Address' of the instruction temporarily as the 'target' and proceed till the end. Later on replace the 'Self Address' by the actual 'Target Address' b the JMP or CALL instructions using the Assemble Command '#A', making use of the act address.

But there is no such problem in the case of Backward JMP and Backward CALL in

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Note 2: The destination Label (ie, the target address) of all Jump instructions must be in the range of -128 bytes (ie, 80H) to +127 (ie,  $7F$  H) bytes relative to the address of the instruction immediately after the Jump instruction. That is, from the current IP location. The relative address of the current IP location is taken as OOH.

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Note 3: While entering mnemonics of instructions, the operands should be separated by comma, without a space. For example. MOV AX.BX (no space permitted between AX and BX). The Hexadecimal numbers can be entered with or with out suffixing of 'H'. For example, MOV AX, 1234H or MOV AX, 1234 (both are valid Hexadecimal numbers).

## 2 (b) Subtraction of Two 16-bit numbers

Aim: To subtract two 16-bit unsigned integer numbers stored in memory locations and to store the 16-bit difference into memory locations. Borrow is to be used as a word, indicating the sign  $(+)$  or  $-)$ .

## Algorithm:

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Assumption: It is assumed that the numbers to be subtracted are stored in consecutive memory locations.

Step 1: Start.

Step 2: Initialise a register to hold borrow, to zero.

Step 3: Bring the first number from memory into another register

Step 4: Subtract the second number from memory from the contents of the above register.

Step 5: If a borrow is not generated, go to Step 8.

Step 6: Increment the Borrow holding register.

Step 7: Take two's complement of the result.

Step 8: Store the result of subtraction into the next consecutive memory location.

Step 9: Store the contents of the Borrow holding register into the next memory location. Step 10: Stop

Accomply Innovage Program



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# 3 (a) Addition of Two 64-bit numbers (Multi-byte addition)

Aim: To add two 64-bit unsigned integer numbers stored in memory locations and to store the 80-bit sum into memory locations.

Theory: Here the addition can be done 'byte by byte' or 'word by word' starting from the least significant byte or word. The instruction for addition is ADC, operating on Byte register or Word register. While using ADC the initial Carry should be cleared.

# Algorithm:

Assumption: It is assumed that the numbers to be added are stored in consecutive memory locations. Also it is assumed that a Word by Word addition is done.

- Step 1: Start.
- Step 2: Initialise a register to hold the word count value, to 4. (The preferred register is CX) Step 3: Clear the Carry flag.
- Step 4: Initialise three memory pointer registers to point to the least significant word locations of the First number, the second number and the result location, in memory.
- Step 5: Bring the word pointed by the first pointer into a register.
- Step 6: Add the word pointed by the second pointer in memory to the contents of the above register using add with carry (ADC) instruction. Store the partial result in memory, making use of the corresponding memory pointer.
- Step 7: Increment the three memory pointes to point to the next word locations. Decrement the word counter. If the counter value is not zero, go to step 5.
- Step 8: Store the Carry generated by the addition of the most significant words, into the result memory locations.

#### Step 9: Stop

#### Assembly language Program:



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(Alternatively, the Last 4 lines of the above can be replaced by):

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# 3 (b) Subtraction of Two 64-bit numbers

Aim: To subtract two 64-bit unsigned integer numbers stored in memory locations and to store the 64-bit difference into memory locations.

# Algorithm:

NUM1:

NUM2:

SUM:

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Assumption: It is assumed that the numbers to be subtraoted are stored in consecutive memory locations. Also it is assumed that a 'Word by Word' subtraction is done and that the Subtrahend is smaller than the Minuend.

Step 1: Start.

Step 2: Initialize a register to hold the word count value, to 4. (The preferred register is CX)

Step 3: Clear the Borrow flag (ie, same as Carry flag)

- Step 4: Initialize three memory pointer registers to point to the least significant word locations of the First number, the second number and the result location, in memory.
- Step 5: Bring the word pointed by the first pointer into a register.
- Step 6: Subtract the word pointed by the second pointer in memory from the contents of the above
	- register using Subtract with borrow instruction. Store the partial result in memory, making use of the corresponding memory pointer.
- Step 7: Increment the three memory pointers to point to the next word locations. Decrement the word
- counter. If the counter value is not zero, go to step 5.



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# Sample Data:



Difference:  $[3500-3507]$   $\rightarrow$   $[BX]$ 

B543 C345 D123 E012

# **CODE CONVERSIONS**

(Note: Read Chapter 10 (Code conversion) of Microprocessor Architecture, Programming and Applications with 8085 by Ramesh Gaonkar, for understanding the need for Code conversions and the algorithms]

# The need for Code conversion

In microcomputer applications, various number systems and codes are used to input data or to display results. The ASCII (American Standard Code for Information Interchange) keyboard is a commonly used input device for microcomputers. Similarly, alphanumeric characters (letters and numbers) are displayed on a display device using the ASCII code. However, inside the microprocessor, data processing is usually performed in binary. In some instances, arithmetic operations are performed in BCD numbers. Therefore data must be converted from one code to another code.

The programming techniques used for code conversion fall into four general categories:

- (i) Conversion based on the position of a digit in a number (eg. BCD to binary and Binary to BCD conversions).
- (ii) Conversion based on sequential order of digits (eg, Binary to ASCII and ASCII to binary).

(iii) Conversion based on hardware consideration (eg. Binary to 7-segment code using table lookup procedure).

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 $11$ 4 (a) BCD to Binary Conversion

Aim: To convert the given two digit packed BCD number to its equivalent binary number.

Theory: BCD represents each of the digits of an unsigned decimal as the 4-bit binary equivalents. Unnacked BCD representation contains only one decimal digit per byte. The digit is stored in the lower nibble; the upper nibble in not relevant to the value of the represented number (usually the upper nibble is zero). Packed BCD representation packs two decimal digits into a single byte.



**Invalid BCD Numbers** 

These binary numbers are not allowed in the BCD code: 1010, 1011, 1100, 1101, 1110, 1111

The conversion uses the principle of positional weighting in a number. To convert a 2-digit packed BCD number into its equivalent binary, first the digits are to be separated into MSD and LSD and then each digit is multiplied by its position value (place value) and added together.

ie. Binary equivalent =  $MSD \times 0AH + LSD$ 

#### Algorithm: 1) Start

- 2) Get the BCD number from memory and store it in a register.
- 3) Separate the LSD of the two-digit packed BCD number (ie, unpack the packed BCD) by ANDing (masking) the packed BCD number with 0FH and storing it in a register.
- 4) Separate the MSD of the packed BCD number by ANDing (masking) the packed BCD number with F0H and shifting the bits 4 times to the right to get the MSD. Multiply the MSD by the place value 10 (0AH).
- 5) Add the Product obtained by multiplication in step 3, with the LSD obtained in step 2
- 6) Stop



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# **Input and Output:**

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First Set of Data:

Input:  $[1100] = 72$  (BCD) Output:  $[1101] = 48$  (Binary in HEX)

#### Second set of Data:

Input:  $[1100] = 99$  (BCD) Output:  $[1101] = 63$  (Binary in HEX)

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# 4 (b) Binary to BCD Conversion

Aim: To convert an 8-bit Binary number to its BCD equivalent.

Theory: An 8-bit unsigned binary number has the range from 00H to FF H. Its BCD equivalent number has the range from 00 to 255 (packed BCD). BCD equivalent number is obtained from the 8-bit binary number by finding the number of 100s (ie, 64Hs), 10s (ie, 0AHs) and 1s (01Hs). Let the most significant digit be BCD. the middle digit be BCD<sub>2</sub> and the least significant digit be BCD<sub>1</sub> Algorithm:

1) Start

- 2) If the binary number is less than 64H (ie, 100dec), go to Step 3; otherwise, divide the binary number by 64H or equivalently, subtract 64H repeatedly until the remainder is less than 64H. The quotient of division is the most significant BCD digit, BCD<sub>3</sub>. (It is the same as the number of times the repeated subtraction is done).
- 3) If the binary number is less than 0AH (ie, 10dec), go to Step 4; otherwise, divide the binary number by 0AH or equivalently, subtract 0AH repeatedly until the remainder is less than 0AH. The quotient of division is the middle BCD digit, BCD<sub>2</sub>. (It is the same as the number of times the repeated subtraction is done).
- 4) The remainder from Step 3 is the least significant BCD digit, BCD<sub>1</sub>.
- 5) Store the three BCD digits obtained in steps 2, 3 and 4 in consecutive memory locations as either (i) unpacked BCD digit for the MSD and two-digit packed BCD digits for the LSD and Middle digit or (ii) three unpacked BCD digits, BCD<sub>3</sub>, BCD<sub>1</sub>, BCD<sub>1</sub> (This is better).  $61$  Ston



Input Data:

**Output Result**  $(2001) = 54$  (Packed BCD)

 $(2002) = 02$  (Most significant digit as unpacked BCD)

(But display of 05, 04, 02 is better)

 $(2000) = FE$ 

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4 (c) HEX digit to ASCII code Conversion<br>Aim: To convert a given Hexadecimal digit (ie, 0, 1,...9, A, B, C, D, E, F) into its equivalent ASCII code in Hex.

# Theory:

Each HEX digit can be converted to an 8-bit ASCII code as shown below. For HEX digit in the range<br>0 to 9, add 30 to get the ASCII code. For HEX digit in the range A to F, add 37 (ie 30+7) to get the ASCII code.



# Algorithm:

1) Start

2) Compare the given HEX digit with '0A'. If it is less than 0A, add 30 to it and Go to step 4. 3) Else, add 30 and 7 to it.

4) Stop

 $(2000) = 07$ 

Input Data (HEX digit): First sample of data:

Output Result (ASCII code in HEX):

 $(2001) = 37H$ 

Second sample of data:  $(2000) = 0B$ 

 $(2001) = 42H$ 

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**Input Data:** 

First sample data:  $(3000) = 33H$ 

 $(3001) = 03H$ 

Output Result (HEX value)

Second sample data:  $(3000) = 42H$ 

 $(3001) = 0BH$ 

## 5 (a) BCD addition

Aim: To add two 4-digit (16-bit) BCD numbers stored in memory

Theory: The 8086 processor will perform only binary addition. Hence for BCD addition, the binary addition of BCD data is performed first and then the Sum is corrected to get the result in BCD. The following is the correction to be done:

- (iv) If the binary sum of lower nibbles of the BCD numbers stored in AL, exceeds 9 or if there is an Auxiliary carry generated from the lower nibble to the upper nibble of the Sum in AL, then 06 is added to the lower nibble of the Sum in AL.
- (v) If the binary sum of upper nibbles of the BCD numbers stored in AL, exceeds 9 or if there is a Carry generated from the upper nibble of the Sum in AL, then 60 is added to the Upper nibble of the Sum in AL.

The correction is automatically done using the DAA instruction.

DAA instruction: Decimal Adjust AL after BCD addition. DAA works on 8-bit only. The result of the addition must be in AL for DAA to work correctly.

#### Algorithm:

1. Start

2. Get the BCD numbers from the memory locations.

3. Add the lower two digits of the 4-digit BCD numbers and adjust for correction using DAA instruction.

4. Add the upper two digits of the 4-digit BCD numbers along with Carry, if any, generated from Step 3 and adjust for correction using DAA instruction.

5. Store the BCD sum and the final Carry in memory locations

6. Stop

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**MNEMONICS** 

**COMMENT** 

#### Input Data:

OFFETT | MACHINE | LABEL



#### Output Result:

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BCD SUM: [2004-2005]: 0811  $[2006]$ : 01

# 5 (b) BCD subtraction

Aim: To subtract two 4-digit (16-bit) BCD numbers stored in memory

Theory: The 8086 processor will perform only binary subtraction. Hence for BCD subtraction, the binary subtraction of BCD data is performed first and then the Difference is corrected to get the result in BCD. The following is the correction to be done:

- If the binary difference of lower nibbles of the BCD numbers stored in AL, exceeds 9 or if there is an Auxiliary carry generated from the lower nibble to the upper nibble of the  $(i)$ difference in AL, then 06 is subtracted from the lower nibble of the Difference in AL. If the binary difference of upper nibbles of the BCD numbers stored in AL, exceeds 9 or
- if there is a Carry generated from the upper nibble of the Difference in AL, then 60 is  $(ii)$ subtracted from the Upper nibble of the Difference in AL.

The correction is automatically done using the DAS instruction.

DAS instruction: Decimal Adjust AL after BCD subtraction. DAS works on 8-bit only. The result of the subtraction must be in AL for DAS to work correctly. Algorithm:

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1. Start

- 2. Get the BCD numbers from the memory locations.
- 3. Subtract the lower two digits of the 4-digit BCD numbers and adjust for correction using DAS instruction.
- 4. Subtract the upper two digits of the 4-digit BCD numbers along with Borrow, if any, generated from Step 3 and adjust for correction using DAS instruction.
- 5. Store the BCD difference and the final Carry (borrow) in memory locations
- 6. Stop



...........

# Input Data:



**Output Result:** 

[2004-2005]: 1755 **BCD Difference:**  $[2006]$ : 00

# Study of MASM and Debug commands and usage of CodeView debugger

Microsoft Macro Assembler masm.exe is used for assembling an 8086 assembly language program. The other files associated with it are link.exe (linker program), ml.exe and ml.err. For debugging and execution. a DOS debugger, debug.exe or Microsoft debugger cv.exe (CodeView) is used. The assembler version used is ver 6.11 and CodeView version used is ver 3.14. DOS debugger gives a command line interface whereas CodeView debugger gives an IDE interface (Integrated Development Environment).

#### Configuration of Path setting:

Store the files masm.exe. link.exe. ml.exe, ml.err, debug.exe, cv.exe and cv.hlp in a folder (named sav. masm) and the folder is placed in a drive (for example under c:\.) The absolute path of this folder is included in the path statement as follows for gaining universal access to the above files from any location (in any drive).

My Computer  $\rightarrow$  Properties  $\rightarrow$  Advanced  $\rightarrow$  Environment Variables  $\rightarrow$  System variables  $\rightarrow$  Path  $\rightarrow$  Edit  $\rightarrow$ Edit System variables  $\rightarrow$  Variable value  $\rightarrow$ 

Here add, after semi colon, the absolute path of the 'masm' folder, after the last entry in the path statement. For example :c:\masm Click ok, ok. ok. (take care not to delete the existing path-do only append).

Alternatively, the above 7 files may be copied in to the 'Current folder' where user programs are stored. But in this case, universal access of 'masm' files are not obtained.

#### **Creating Source file and Assembling:**

Create an 8086 ALP source file with extension .asm using any text editor such as notepad, edit.com, Norton editor, wordpad etc. The file name should not exceed 8 characters in length and file extension is 3 characters. Go to the DOS command prompt. In Windows XP: start  $\rightarrow$  run  $\rightarrow$  cmd Now a default folder is displayed. (For example: c:\Documents and settings\Prog>). Under this folder create a user folder to store the user files namely: .asm, .lst, .obj and .exe files. For assembling the source file, use the following command: If the source file is add.asm, type the command as:

#### c:\...\user> masm.exe /la add.asm

(here .exe extension and .asm extension are optional) ( /la means list all)

(That is, you can even type: c:\...\user>masm /la add)

This will assemble the source file and generate two files: add.lst and add.obi (Note: For exiting from DOS Command Window, use 'exit' command) The command summary of masm can be obtained by the command: masm /? Usage: masm /options source(.asm),[out(.obj)],[list(.lst)],[cref(.crf)][;]

- Generate cross-reference  $/c$
- /D<svm>f=<val>l Define symbol



- $\overline{X}$ List false conditionals
- Generate symbolic information for CodeView  $IZi$
- Generate line-number information /Zd

# Linking the .obj file, debugging and running the .exe file:

Type the command as:

 $c:\$ ...... \user> link.exe add.obj

(here .exe extension and .obj extension are optional)

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(That is, you can even type: c:\...\user>link add)

If a semicolon is typed after . Obj the prompt options will not be asked.

ie., type  $c:\dots$  \user> link add:

Here. add.exe file is created.

Since .exe files are self executing files, the file name can be given as a dos command in the dos command promot for running the program and for observing the result. (note:- if a display routine is written in the main program a display can be seen in the screen – other wise nothing can be seen).

Alternatively, the .exe file can be loaded into memory, debugged and executed using DOS debugger (debug.exe) or Microsoft debugger cy.exe (CodeView).

#### **CodeView Debugger:**

Microsoft debugger CodeView (cv.exe) (version 3.14) can be used for loading the exe file to memory, debugging and executing. CodeView gives an IDE interface (Integrated Development Environment) and is a better debugger than DOS debugger debug.exe.

Usage:  $c$ : \, \, \, \, \, \, \, \, cv, exe add.exe (.exe extension of cv and add are optional)

(That is, you can even type: c:\...\user>CV add). In the CV Window, go to the 'Run' menu, click 'Restart' and then click 'Animate' for running the Program.

The Result of execution can be observed in Memory by typing the following command in the CV command prompt: For example:  $> d$  ds: 0 8 (where 8 is the no. of bytes 'n' to be displayed).

#### **DOS Debugger:**

Alternatively, DOS Debugger can also be used. Type the command as: 

(That is, you can even type:  $c:\dots$  user>debug add.exe)

Now the debug command prompt, hyphen, is displayed. The debug command summary is obtained by:  $-2$ 

To execute the user program add.exe, give the debug command as:

 $-g = 0000$  xxxx where 0000 is the starting offset address and xxxx denotes the ending offset address. The ending offset address (which is a break point) can be obtained from the offset address of the MOV AH, 4CH instruction displayed in the .lst file. The result of execution can be observed in memory by the debug command: -d ds:0000 (if no ending offset address is given, 128 bytes will be displayed by default). The result of execution can also be observed in registers using the debug command-r. (Note: For exiting from DOS Debugger Window, use 'a' command (quit))

#### Example:

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(1) To add two 16-bit unsigned numbers stored in memory and to get the 32-bit sum in memory: add.asm

MODEL SMALL .STACK 1000H

These dot directives define the stack segment. This will avoid the warning indication namely, "Warning: no stack segment" during the Linking process. These are not absolutely necessary.

- :Logical Data Segment DATA1 begins
- DATA1 **SEGMENT NUM1** 
	- DW 1234H :DW is a directive to tell the assembler to reserve two successive memory
		- ; locations for a word type variable, to store the values in those memory
			- ; locations and to assign the name NUM1 to the first memory location.ie The
		- : First byte. NUM1 can be considered as an array of one word.
- NUM<sub>2</sub> DW 0F562H : Pre-fix 0 for hexadecimal numbers starting with A to F.



;Logical Code Segment CODE1 begins

#### **SEGMENT CODE1**

ASSUME CS:CODE1, DS:DATA1 ;lt is a directive to tell the assembler to use a logical segment named CODE1 as the Physical Code Segment and to use a logical segment named DATA1 as the Physical Data Segment for the user's program START: MOV AX, DATA1 :To initialize the Data Segment register DS. Segment Registers cannot be :directly loaded with an immediate number. The number is to be loaded MOV DS, AX : first to a general purpose register and then from that register ; to the Segment register. DS holds the upper 16-bit of the Base Address :(ie, the upper 16-bit of the Starting address of the physical Data Segment) MOV CX, 0000H; Initializes the Carry holding register MOV AX, NUMI  $1234 \text{ H} +$ ADD AX, NUM2 F562 H INC<sub>L1</sub> 0001 0796 H (32-bit sum) INC CX MOV SUM, AX  $Li:$ eg. ADD AX, NUM2

#### MOV SUM+2,CX  $(AX) \leftarrow (AX) + NUM2$  (symbolic illustration) :DOS function Call to terminate the execution of the user program and to exit MOV AH, 4CH to DOS command prompt **INT 21H**

**CODE1 ENDS** 

: END directive indicates end of assembly. **END START** 

Syntax of ADD instruction: ADD <destination>, <source>

where destination is a register or a memory location specified in one of 24 different ways and source is an immediate number or a register or a memory location specified in one of 24 different ways. Destination and Source cannot be both memory locations in the same instruction.

# Syntax of MOV instruction: MOV <destination>, <source>

where destination is a register or a memory location specified in one of 24 different ways and source is an immediate number or a register or a memory location specified in one of 24 different ways. Destination and Source cannot be both memory locations in the same instruction.



Difference

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# 24 Different ways of specifying Memory Locations

Only, index registers SI and DI and base registers BX and BP can be used as memory pointers.



Notel: No stack segment is defined in the above program and is left out because DOS automatically allocates a 128-byte stack for all programs. The Linker program indicates a warning message saying that no stack is present. The instruction that uses stack in the program is INT 21H which Calls a procedure in DOS. This warning can be ignored because the Stack memory used here is fewer than 128 bytes.

# Note2: Signed 8-bit numbers and Overflow Flag:

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D7 is the sign bit. D7 is zero for positive numbers and D7 is 1 for negative numbers. The magnitude of negative number is represented in 2's complement form (ie for D6 to D0 bits). Consider 3 Cases:



Here, since D7 is 1, the magnitude of the result (ie, D6 to D0 bits) is in 2's complement form. ie, D6 to D0 namely, 010 0110 is in 2's complement form. To get the answer, take 2's complement of the magnitude. We get 101 1010 . ie 5A or 90 dec. That is, the answer is -90 dec which is Incorrect. Therefore the overflow flag OV is Set to 1.



Here, since D7 is 1, the magnitude of the result (ie, D6 to D0 bits) is in 2's complement form. ie, D6 to D0 namely, 000 0010 is in 2's complement form. To get the answer, take 2's complement of the magnitude. Weiget 000 0011 . ie 03 or 3 dec. That is, the answer is -3 dec which is Incorrect. Therefore the overflow flag OV is Set to 1.



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dec which is Incorrect. Therefore the overflow flag OV is Set to 1. Question: When is the Oveflow Flag Set to 1? It will be Set to 1, if there is a Carry from D6 to D7 or from D7, but not from both.

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 $-7-$ (2) To subtract two 16 bit unsigned numbers stored in memory and to get the 32 bit difference in memory. the high order word being a sign indicator :sub.asm Syntax: SUB <destination>, <source> **DATA1 SEGMENT** (an immediate number) NUMI DW 1243H  $(a \text{reg})$ or NUM2 DW 0F231H  $\alpha$ r  $(a \rceil c g)$ DW 2 DUP(0) **DIFF** (a mem. loc.)  $or$ **DATAI ENDS** (a mem. loc.) Destination and Source cannot be both memory locations **CODE1 SEGMENT** in the same instruction. CS:CODE1, DS:DATA1 **ASSUME** START: MOV AX, DATA1 MOV DS. AX MOV CX, 0000H; CX holds borrow SUB AX, NUM2 MOV AX, NUMI  $(AX) \leftarrow (AX) - NUM2$ SUB AX, NUM2 **JNC LI INC CX** NEG AX ; it takes the 2's complement of the difference, if the result if negative. 'LI: MOV DIFF, AX  $1243$  H -MOV DIFF+2, CX F231 H 2012 H MOV AH, 4CH (the result is a negative number in 2's complement form - taking 2's complement of the **INT 21H** result gives the actual answer - 2's complement of 2012 gives DFEE - the borrow flag (ie, carry flag) = 1, is a sign indicator. The actual answer can also be obtained by doing **CODE1 ENDS** the subtraction 'Larger number' minus 'Smaller number' and prefixing a minus sign. ie, **END START**  $F231 - 1243 \rightarrow -DFEE$  $\bullet$ (3) To multiply two 16 bit unsigned numbers stored in memory and to get the 32 bit product in memory ;mul.asm **DATA1 SEGMENT** MULTIPLICAND DW 204AH DW 3B2AH **MULTIPLIER** DW 2 DUP(0) **PRODUCT** Syntax: MUL <source> {bytexbyte or wordxword multiplication} **DATAI ENDS** y3 (Source is the multiplier which is a byte or a word in a reg)  $\overline{a}$ CODE1 SEGMENT ASSUME CS:CODE1, DS:DATA1 (is the multiplier which is a byte or a word in a mem. Loc.) START: MOV AX, DATAI MOV DS, AX Product  $\leftarrow$  Multiplicand  $\times$  Multiplier MOV AX, MULTIPLICAND For Byte × Byte multiplication, the Multiplicand is in AL and the **MUL MULTIPLIER** product is in AX by dafult. For Word × Word multiplication, the MOV PRODUCT, AX Multiplicand is in AX and the product is in DX AX by default. **MOV PRODUCT+2, DX** Eg, 204A H × MOV AH, 4CH 3B2A H **INT 21H** 0776 5A24 H **CODE1 ENDS END START** 16.12.2014 Dept. of CSE MBCET (For Private Circulation only)





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 $\vdots$ 



 $-15-$ **CODE SEGMENT ASSUME CS:CODE, DS:DATA** .. START: MOV AX, DATA MOV DS, AX MOV BX, COUNT-1 :BX is the Pass counter :CX is the Comparison counter which is initialised to the Pass counter MOV CX, BX  $L3:$ value at the beginning of each Pass MOV SI, OFFSET LIST MOV AL, [SI]  $L2:$ CMP AL. [SI+1] :Jump if the ith no.is Greater than or Equal to the (i+1)th no. JGE LI XCHG AL. [SI+1] MOV [SI], AL :or use INC SI ADD SI, 01  $LI:$ DEC CX JNZ L<sub>2</sub> DEC BX JNZ L3 MOV AH, 4CH **INT 21H** CODE **ENDS END START** :(17) to sort 8-bit signed nos in ascending order - ascends.asm **DATA SEGMENT** 7FH, 00H, 0FFH, 80H LIST DB **COUNTEOU** 04H **ENDS DATA** CODE **SEGMENT ASSUME CS:CODE, DS:DATA START: MOV AX, DATA** MOV DS, AX MOV BX, COUNT-1 :BX is the Pass counter ;CX is the Comparison counter which is initialised to the Pass counter MOV CX, BX  $L3:$ :value at the beginning of each Pass MOV SI. OFFSET LIST MOV AL. [SI]  $L2:$ **CMP AL, [SI+1]** :Jump if the ith no.is Less than or Equal to the (i+1)th no. JLE LI XCHG AL, [SI+1] MOV [SI], AL ADD SI, 01 ;or use INC SI  $Li:$ DEC CX JNZ L<sub>2</sub> DEC BX JNZ L3 MOV AH, 4CH **INT 21H ENDS** CODE **END START** 

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-17-: instead of ADC
              MOV AL, [SI]
              ADD AL, [DI] ; since it is not a multibyte addition, ADD can be used instead of ADC
              INC LI
              INC AH
              MOV [BX], AX
       L1:INC SI
              INC DI
               ADD BX, 02 ; add 02 since the result matrix elements are of type word \frac{1}{x} or use INC BX
                              :twice - CY is automatically taken care of here since the result
                              :elements are of word type
               DEC CX
              JNZ NEXT
               MOV AH, 4CH
               INT 21H
CODE
               ENDS
               END START
String Instructions
A string is a series of bytes or words stored in successive memory locations. Often a string consists of a
series of ASCII character codes.
    1) Move String Instructions
             MOVS/MOVSB/MOVSW
        These are used for moving (copying) a byte or a word from a location in the data segment to a location
        in the extra segment.
        There are three forms for the syntax:
        a) MOVS <dst_str>, <src_str>; dst_str can be a reg or a mem.loc and src_str can be a reg or
            mem.loc or an immediate number (Can both be memory locations? Can both be registers? - verify)
        b) MOVSB
                          - No operands specified here
        c) MOVSW
        The offset address of the source byte or word in the data-segment must be in the SI Register.
        (ie, SI should point to a byte or word in the Data Segment)
        The offset address of the destination location in the extra-segment must be contained in the DI Register.
        (ie, DI should point to a byte or word in the Extra Segment)
        For multiple-byte or multiple-word moves, the number of elements to be moved is put in the CX register
        and CX acts as a down counter.
        After a byte or a word is moved, SI and DI are automatically adjusted to point to the next source and
        next destination locations (ie, it can be either auto-increment or auto-decrement, depending on the
         value of the Direction Flag, DF)
        If the Direction Flag is reset (= 0) using CLD instruction, then SI and DI will be auto-incremented by 1
        for byte movement and by 2 for word movement.
        If the Direction Flag is set (= | ) using STD instruction, then SI and DI will be auto-decremented by 1 for
         byte movement and by 2 for word movement.
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CODE **SEGMENT** ASSUME CS:CODE, DS:DATA, ES:DATA **START:** 

MOV AX, DATA MOV DS, AX MOV ES, AX MOV AX, PWDSTR LEN CMP AX. INPUTSTR LEN JNZ L1 : same as JNE **LEA SI, PWDSTR** LEA DI, INPUTSTR MOV CX, PWDSTR LEN CLD REPE CMPSB ; or (REPE CMPS INPUTSTR, PWDSTR) JNZ L1 :: this checks the zero flag - same as JNE

- DISP CORRECT JMP L<sub>2</sub>
- DISP INCORRECT LI:
- $L2:$ MOV AH, 4CH **INT 21H**

CODE

**ENDS END START** 

3) Scan String Instructions (Scan or search a string for a Byte or a word)

# **SCAS / SCASB / SCASW**

There are three forms for the syntax: a) SCAS <dst str>

b) SCASB - No operands specified here c) SCASW

When a match is found (ie, when the two elements are the same) Zero flag is SET

These are used for searching (scanning) through a string to find if it contains a specified string byte or string word. This compares a byte in 'AL' or a word in 'AX' with a byte or word pointed to by DI in Extra Segment. The string to be scanned must be in Extra Segment, and DI must contain the offset of the byte or word to be compared. The length of the string must be stored in CX.

If the Direction Flag is reset  $(= 0)$  using CLD instruction, then DI will be auto-incremented by 1 for byte comparison and by 2 for word comparison.

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to second operand) the Zero flag will be Set and the program will exit to DOS.

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### **DOS and BIOS interrupts**

Software interrupts are the primary means to access the services of an operating system. The DOS (Disk Operating System) and BIOS (Basic Input Output system) provide a large number of functions to access devices. files, memory and process control services that are available to any program which is capable of setting registers and invoking software interrupts.

DOS and BIOS services for device access such as reading from Keyboard, writing to screen, disk read, disk write etc. communicates in ASCII format. For example, the numeric Key '1' on keyboard is read as the ASCII code 31H. The numeric value '1' can be displayed on the screen by writing the ASCII code 31H on to the screen. Therefore the ASCII codes read from the keyboard have to be converted to 'numeric data' for processing and back to ASCII form for displaying on the screen. This process is required for numeric data processing.

The operating system service access interface is called 'System Call'. The services provided by INT 21H (Software Interrupts) are called DOS services or DOS function (system) call. DOS interrupts and the corresponding services are listed below.

#### **DOS INTERRUPTS:**



#### For example, consider DOS System Call (Function Call) INT 21H:

The DOS services INT 21H are categorized into various 'Functions'. The function numbers vary from Function 00H to Function 63H. Some of the functions are:

INT 21H, Function 00H : Program Terminate

INT 21H, Function 01H : Read Character from Standard Input Devices (ie, Keyboard)

INT 21H, Function 02H : Write Character to Standard Output Devices (ie, Display Monitor)

INT 21H. Function 03H : Read Character from Standard Auxiliary Input Devices (ie, Serial Port COMI)

INT 21H, Function 09H : Display String to Standard Output Devices (ie, Display Monitor)

INT 21H. Function 4CH : Terminate execution with Return Code

etc.

The steps involved in accessing DOS Interrupts are:

(i) Load a Function Number in the AH register. If there is a sub-function, its value is stored in AL register. That is, use instructions such as MOV AH, function\_num\_and\_MOV AL, sub-function\_num

(ii) Load other registers, if required, as specified in the DOS service format.

(iii) Prepare Buffers, ASCIIZ (zero terminated string), and control blocks, if necessary.

(iv) Invoke DOS service INT n

(v) Process Response: Look for the error indicators by examining the carry flag and error code register (generally AX) as set by the DOS service Call. The system call communicates results through register parameters.

BIOS is the lowest level software in the PC. Even DOS uses BIOS functions to control the hardware. BIOS service functions are supplied by the manufacturer of the hardware device.



# For example, consider BIOS Function Call INT 10H:

The BIOS function call INT 10H are categorized into various 'Functions'. The function numbers vary from Function 00H to Function FFH. Some of the functions are:

INT 10H, Function 00H : Set Video Mode

INT 10H. Function 01H : Set Cursor Shape

INT 10H, Function 02H : Set Cursor Position

INT 10H, Function 03H : Read Cursor Position. etc

The steps involved in accessing BIOS Interrupts are:

(i) Load a Function Number in the AH register. If there is a sub-function, its value is stored in AL register. That is, use instructions such as MOV AH, function num and MOV AL, sub-function num

(ii) Load other registers, if required, as specified in the BIOS service format.

(iii) Prepare Buffers, ASCIIZ (zero terminated string), and control blocks, if necessary.

(iv) Invoke BIOS service INT n

(v) Process Response: Look for the error indicators by examining the carry flag and error code register (generally AX) as set by the BIOS service Call. The system call communicates results through register

parameters.



Syntax of Some functions of DOS function Call INT 21H



(25) DOS function call to Read a character from the keyboard and to echo the character on to the screen, with suitable message string

INT 21H-function 01H (here ASCII code of the input key is returned to AL register)

;int21\_01.asm

 $\bullet$ 

:Macro is defined DISP\_STR MACRO MSG MOV AH, 09H

: 'MSG' is the dummy argument

MOV DX, OFFSET MSG

Any number of dummy arguments can be used. For example, MACRO NAME MACRO <argl>, <arg2>, ..., <argn> MACRO can also be defined without any dummy arguments.

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INT<sub>21</sub>H

**ENDM** 

**DATA SEGMENT MSG1** DB Type any key: S': ; MSG1 is the actual argument **DATA ENDS** 

```
CODE
          SEGMENT
```
 $\bullet$ 

**ASSUME CS:CODE, DS:DATA** 

**START: MOV AX, DATA** MOV DS, AX

DISP STR MSGI

;here macro is 'Called' - MSGI is the Actual argument. Actual parameter is passed from Calling program to the Dummy argument in the Macro definition

MOV AH, 01H ; This function Reads a Character from Key Board with simultaneous echoing of the character on the Screen. The ASCII code of the input Key is returned to the AL register.  $INT 21H$ 



(26) DOS function call to display the ASCII character whose ASCII code is stored in DL register

#### INT 21H-function 02H

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;int21\_02.asm **DATA SEGMENT** DB 'Hello world - DOS function Call INT 21H, function 02H' **MSG** LEN EQU (\$-MSG) **DATA ENDS** CODE **SEGMENT ASSUME CS:CODE, DS:DATA START: MOV AX, DATA** MOV DS, AX MOV CX, LEN MOV SI, OFFSET MSG MOV AH, 02H ;this function call displays the ASCII character whose ASCII code is stored in DL register NEXT\_CHAR: MOV DL, [SI] ;The ASCII code pointed by the SI pointer is stored in DL register **INT21H** INC SI LOOP NEXT\_CHAR MOV AH, 4CH **INT 21H** CODE **ENDS END START** 16.12.2014 Dept. of CSE MBCET (For Private Circulation only)

